
Supplemental Material: Maximizing Induced Cardinality Under a Determinantal Point Process

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1 Monotonicity of Induced Cardinality

The monotonicity of f is a straightforward application of the Cauchy eigenvalue interlacing theorem.

Theorem 1. Cauchy interlacing theorem: Consider a symmetric matrix $A \in \mathbb{R}^{n \times n}$ with eigenvalues $\alpha_1 \leq \alpha_2 \leq \dots \leq \alpha_n$, and any principal submatrix $B \in \mathbb{R}^{m \times m}$ with eigenvalues $\beta_1 \leq \beta_2 \leq \dots \leq \beta_m$. Then the eigenvalues interlace in the following manner:

$$\alpha_k \leq \beta_k \leq \alpha_{k+n-m} \quad \text{for } k = 1, 2, \dots, m. \quad (1)$$

Theorem 2. $f(S)$ is monotone increasing.

Proof. Given two sets $S \subseteq T \subseteq [n]$, we will show that $f(S) \leq f(T)$. Denote the eigenvalues of L_T by $\alpha_1 \leq \alpha_2 \leq \dots \leq \alpha_{|T|}$, and the eigenvalues of L_S by $\beta_1 \leq \beta_2 \leq \dots \leq \beta_{|S|}$. Since L_S is a principal submatrix of L_T , the Cauchy interlacing theorem implies that:

$$\alpha_k \leq \beta_k \leq \alpha_{k+|T|-|S|} \quad \text{for } k = 1, 2, \dots, |S|. \quad (2)$$

We will combine this fact with the eigenvalue version of the formula for $f(S)$ to get the desired inequality:

$$\begin{aligned} f(S) &= |S| - \sum_{i=1}^{|S|} \frac{1}{\beta_i + 1} \leq |S| - \sum_{i=1}^{|S|} \frac{1}{\alpha_{i+|T|-|S|} + 1} \\ &\leq |S| - \sum_{i=1}^{|S|} \frac{1}{\alpha_{i+|T|-|S|} + 1} + \sum_{i=1}^{|T|-|S|} \left(1 - \frac{1}{\alpha_i + 1}\right) \\ &= |T| - \sum_{i=1}^{|S|} \frac{1}{\alpha_{i+|T|-|S|} + 1} - \sum_{i=1}^{|T|-|S|} \frac{1}{\alpha_i + 1} \\ &= |T| - \sum_{i=1}^{|T|} \frac{1}{\alpha_i + 1} = f(T), \end{aligned}$$

where the first inequality is an application of the interlacing theorem, and the second follows because the quantity being added is positive ($0 \leq \alpha_i$ since L is a positive semi-definite matrix). \square

2 Fractional Subadditivity of Induced Cardinality

Before proving fractional subadditivity, we state two matrix algebra facts that will be useful in completing the proof. The first follows from the definition of the adjugate matrix, and the second from the submodularity of $\log \det$.

18 **Lemma 2.1.** For an invertible matrix $A \in \mathbb{R}^{n \times n}$, $\text{Tr}(A^{-1}) = \sum_{i=1}^n \det(A_{-i}) / \det(A)$, where
 19 $A_{-i} \in \mathbb{R}^{(n-1) \times (n-1)}$ is the A matrix with its i th row and column removed.

20 *Proof.* The adjugate matrix $\text{adj}(A)$ is defined as the matrix that satisfies $\det(A)I = A\text{adj}(A)$. This
 21 matrix is known to be the transpose of the cofactor matrix of A . More concretely, let M_{ij} denote the
 22 (i, j) -minor of the matrix $A \in \mathbb{R}^{n \times n}$ (the determinant of the matrix formed by deleting row i and
 23 column j from A). Let $C_{ij} = (-1)^{i+j}M_{ij}$ denote the corresponding cofactor. The adjugate matrix
 24 $\text{adj}(A)$ equals C^\top . Plugging C^\top into the definition of the adjugate: $\det(A)I = AC^\top$. Multiplying
 25 by A^{-1} and taking the trace:

$$\det(A) \text{Tr}(A^{-1}) = \sum_{i=1}^n (-1)^{i+i} M_{ii} = \sum_{i=1}^n \det(A_{-i}). \quad (3)$$

26 Dividing by $\det(A)$ yields the desired identity. \square

27 Second, from the submodularity of $\log \det$, we have the following useful lemma.

28 **Lemma 2.2.** For any set $T_i \subseteq T$ and any $j \in T_i$:

$$\frac{\det(L_{T_i \setminus j} + I)}{\det(L_{T_i} + I)} \leq \frac{\det(L_{T \setminus j} + I)}{\det(L_T + I)}. \quad (4)$$

29 *Proof.* The function $g(S) = \log \det(L_S + I)$ is a well-known submodular function. From the
 30 definition of submodularity, we can say that for any set $T_i \subseteq T$ and any $j \in T_i$, the following
 31 inequality holds:

$$g(T_i) - g(T_i \setminus j) \geq g(T) - g(T \setminus j). \quad (5)$$

32 Writing out the expression for g and combining logs:

$$\log \left(\frac{\det(L_{T_i} + I)}{\det(L_{T_i \setminus j} + I)} \right) \geq \log \left(\frac{\det(L_T + I)}{\det(L_{T \setminus j} + I)} \right).$$

33 Exponentiating and then taking the inverse yields the desired expression. \square

34 We are now ready to prove fractional subadditivity of $f(S)$.

35 **Theorem 3.** $f(S)$ is fractionally subadditive.

36 *Proof.* Let S , T_i , and α_i satisfy the relationship $\sum_{i:j \in T_i} \alpha_i \geq 1$ for all $i \in S$. Then $\{T_i\}$ must cover
 37 S , in the sense that $S \subseteq \bigcup_i T_i$. (If some element $s \in S$ were not in any of the T_i , then we would
 38 have $\sum_{i:s \in T_i} \alpha_i = 0$.) Hence, by monotonicity (Theorem 2), $f(S) \leq f(\bigcup_i T_i)$. Let $T = \bigcup_i T_i$ and
 39 $M = L_T$. Then we can write:

$$\begin{aligned} f(S) &\leq f(T) = \text{Tr}(I - (M + I)^{-1}) && \text{(definition of } f) \\ &= \sum_{j \in T} \left(1 - \frac{\det(M_{-j} + I)}{\det(M + I)} \right) && \text{(by Lemma 2.1)} \\ &\leq \sum_{j \in T} \left(\sum_{i:j \in T_i} \alpha_i \right) \left(1 - \frac{\det(M_{-j} + I)}{\det(M + I)} \right) && \text{(multiplication by value } \geq 1) \\ &= \sum_i \alpha_i \sum_{j \in T} \left(1 - \frac{\det(M_{-j} + I)}{\det(M + I)} \right) && \text{(switching the order of the summations)} \\ &\leq \sum_i \alpha_i \sum_{j \in T} \left(1 - \frac{\det(L_{T_i \setminus j} + I)}{\det(L_{T_i} + I)} \right) && \text{(by Lemma 2.2)} \\ &= \sum_i \alpha_i \sum_{j \in T_i} \left(1 - \frac{\det(L_{T_i \setminus j} + I)}{\det(L_{T_i} + I)} \right) && \text{(dropping zero terms)} \\ &= \sum_i \alpha_i \text{Tr}(I - (L_{T_i} + I)^{-1}). && \text{(by Lemma 2.1)} \end{aligned}$$

40 Thus, $f(S) \leq \sum_i \alpha_i f(T_i)$. \square

41 **3 NP-Hardness of Induced Cardinality**

42 Before showing that $f(S)$ is NP-hard to maximize, we first state a lemma that will be helpful in this
43 proof.

44 **Lemma 3.1.** For a vector $\lambda \in \mathbb{R}^k$, define the function $h(\lambda) = \sum_{i=1}^k \frac{\lambda_i}{\lambda_i + 1}$. Then $\lambda = \mathbf{1}$ is the
45 unique maximizer of the following optimization problem:

$$\max_{\lambda} h(\lambda) \text{ s.t. } \sum_{i=1}^k \lambda_i = k. \quad (6)$$

46 *Proof.* Introducing a Lagrange multiplier α for the equality constraint, we have the following
47 Lagrangian function:

$$\mathcal{L}(\lambda, \alpha) = h(\lambda) - \alpha \left(k - \lambda^\top \mathbf{1} \right). \quad (7)$$

48 According to the method of Lagrange multipliers, if λ^* is a maximizer of h for the original constrained
49 problem, then there exists an α^* such that (λ^*, α^*) is a stationary point of \mathcal{L} . Hence, a maximizer of
50 the original problem must occur at a point where all of the partial derivatives of \mathcal{L} are zero. These
51 derivatives are:

$$\frac{\partial \mathcal{L}}{\partial \lambda_i} = \frac{1}{(\lambda_i + 1)^2} - \alpha \quad \text{and} \quad \frac{\partial \mathcal{L}}{\partial \alpha} = k - \sum_{i=1}^k \lambda_i \quad (8)$$

52 For it to be the case that $\frac{\partial \mathcal{L}}{\partial \lambda_i} = 0$ for all i , it must be true that $\frac{\partial \mathcal{L}}{\partial \lambda_i} = \frac{\partial \mathcal{L}}{\partial \lambda_j}$ for all i, j . This can only
53 hold if $(\lambda_i + 1)^2 = (\lambda_j + 1)^2$, which is only true when $\lambda_i = \lambda_j$. So at any stationary point of \mathcal{L} it
54 must be the case that λ is a uniform vector. Satisfying $\frac{\partial \mathcal{L}}{\partial \alpha} = 0$ sets the scale of this vector, requiring
55 $\lambda_i = 1 \forall i$. \square

56 We are now ready to prove the main NP-hardness result.

57 **Theorem 4.** MIC is NP-hard.

58 *Proof.* Recall the EXACT 3-COVER (X3C) problem: Given a set S and a collection C of size-3
59 subsets of S , decide if there is a sub-collection $C' \subseteq C$ that contains every element of S exactly once.

60 We will reduce this to MIC with the following construction. (The DPP kernel construction is
61 identical to that of Theorem 2.4 in Kulesza [2012].) First, define a $|C| \times |S|$ matrix F with entries
62 $F_{cs} = \mathbf{1}(s \in C_c) \frac{1}{\sqrt{3}}$. Let $L = FF^\top$. This is a $|C| \times |C|$ positive semi-definite matrix with entries:

$$L_{ij} = \frac{|C_i \cap C_j|}{3}.$$

63 Set $k = \frac{|S|}{3}$. We will now show that $\text{MIC} \geq \frac{k}{2}$ if and only if an exact 3-cover exists.

64 • If an exact 3-cover exists, then $\text{MIC} \geq \frac{k}{2}$: Without loss of generality, let $\{C_1, \dots, C_k\}$ be a
65 collection of size-3 sets that make up an exact 3-cover, and let $Y = \{1, \dots, k\}$. Then, by
66 construction, for $i, j \in Y, i \neq j$, we have $L_{ij} = 0$ and $L_{ii} = 1$; that is, L_Y is the identity
67 matrix. From the equation for f in terms of eigenvalues, with λ_i denoting the eigenvalues of
68 L_Y , we have:

$$f(Y) = \sum_{i=1}^k \frac{\lambda_i}{\lambda_i + 1} = \sum_{i=1}^k \frac{1}{1 + 1} = \frac{k}{2}. \quad (9)$$

69 • If an exact 3-cover does not exist, then $\text{MIC} < \frac{k}{2}$: We begin by constructing a relaxation,
70 RELAXED-MIC. The MIC solution can be no larger than the solution to RELAXED-MIC.
71 We will then show that RELAXED-MIC has maximum value $\frac{k}{2}$, and that any solution to
72 MIC that also achieves this value must correspond to an exact 3-cover.

73 First, note that the diagonal of L is all 1's, so the trace of any size- k principal submatrix is k .
 74 Since the trace of a matrix is also the sum of its eigenvalues, we have that for any size- k set
 75 Y :

$$\text{Tr}(L_Y) = \sum_{i=1}^k \lambda_i = k, \quad (10)$$

76 where λ_i are the eigenvalues of L_Y . Now recall the eigenvalue form of $f(S)$:

$$f(Y) = \sum_{i=1}^k \frac{\lambda_i}{\lambda_i + 1}. \quad (11)$$

77 If we combine this expression with the constraint on the sum of the eigenvalues, then we get
 78 a relaxation of the MIC problem:

RELAXED-MIC :

$$\max_{\lambda_1, \dots, \lambda_k} \sum_{i=1}^k \frac{\lambda_i}{\lambda_i + 1} \quad \text{s.t.} \quad \sum_{i=1}^k \lambda_i = k. \quad (12)$$

79 This problem is identical to MIC, but with fewer constraints, since it does not require that
 80 the λ_i exactly match the eigenvalues of a size- k submatrix of L . From Lemma 3.1, we know
 81 that the unique maximizer of this relaxed problem is $\lambda_1 = \dots = \lambda_k = 1$. This solution has
 82 value $\frac{k}{2}$. Thus, the value achieved by MIC must be $\leq \frac{k}{2}$.

83 We now argue that MIC only achieves this value when there is a submatrix of L that
 84 corresponds to an exact 3-cover. Since $\lambda = 1$ is the *unique* maximizer of RELAXED-MIC,
 85 no other setting of λ can achieve a value as large as $\frac{k}{2}$. Given the construction of the matrix
 86 L , the only size- k submatrix with exactly this set of all-1 eigenvalues is the identity matrix.
 87 But if there exists a size- k submatrix of L that is the identity matrix, then this corresponds
 88 to an exact 3-cover, which contradicts the premise that no exact 3-cover exists.

89 □

90 4 Proof of Uniform Approximation Bound

91 **Corollary 4.1.** *For all sets S of size k ,*

$$\frac{f(S)}{\hat{f}(S)} \geq 1 - \frac{mr'(B, k, 3)}{(m-1)k - r'(B, k, 1) - r'(B, k, 2)}, \quad \text{with } r'(B, k, \ell) = \sum_{j=n-k+1}^n \left(\frac{\lambda_j(B)}{m} \right)^\ell. \quad (13)$$

92 *Proof.* By the Cauchy eigenvalue interlacing theorem, the eigenvalues of B_S interlace those of B
 93 such that: $\lambda_i(B) \leq \lambda_i(B_S) \leq \lambda_{i+n-k}(B)$. Thus:

$$\text{Tr}(B_S) = \sum_{j=1}^k \lambda_j(B_S) \leq \sum_{j=1}^k \lambda_{j+n-k}(B) = \sum_{j=n-k+1}^n \lambda_j(B). \quad (14)$$

94 Hence the trace of B_S is upper-bounded by the sum of the top k eigenvalues of B . Since raising a
 95 matrix to a power simply raises its eigenvalues to that power, we also have:

$$\text{Tr}(B_S^i) \leq \sum_{j=n-k+1}^n \lambda_j(B)^i, \quad (15)$$

96 and therefore $r(B_S, \ell) \leq r(B, k, \ell)$.

97 We can now substitute $r'(B, k, \ell)$ for $r(B_S, \ell)$ in the original theorem, noting that these terms have
 98 positive coefficients in the numerator and negative coefficients in the denominator. □

99 References

100 A. Kulesza. *Learning with Determinantal Point Processes*. PhD thesis, University of Pennsylvania,
 101 2012.